What's wrong with RANS? or How to read results of RANS (CFD) simulations?





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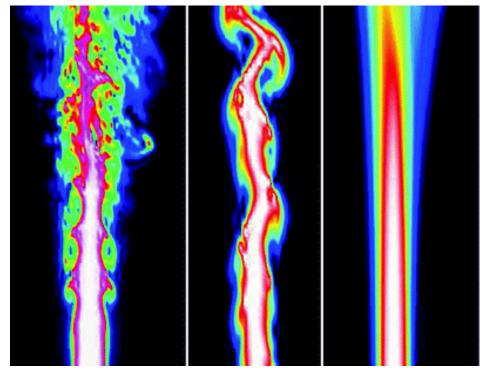
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DNS/LES/RANS - the difference



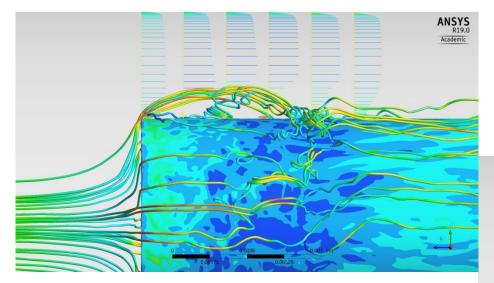


DNS (left), LES (middle) and RANS (right) predictions of a turbulent jet. LES requires less computational effort than DNS, while delivering more detail than the inexpensive RANS

Source: Maries A. et al. (2012), DOI: 10.1007/978-3-642-27343-8_7

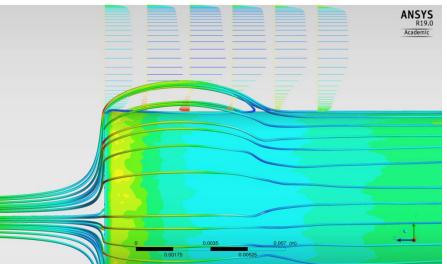






LES (selected instant)

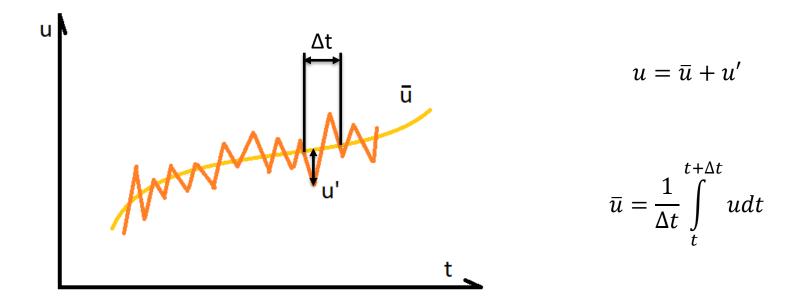
• LES (time-averaged) \cong RANS





Time averaging – the essence of RANS

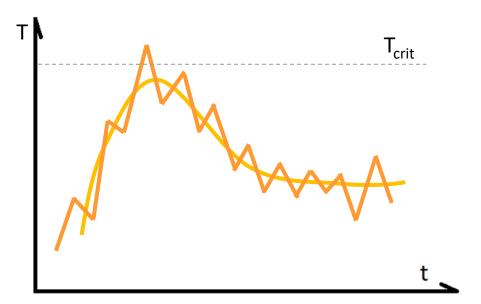






Time averaging – the essence of RANS

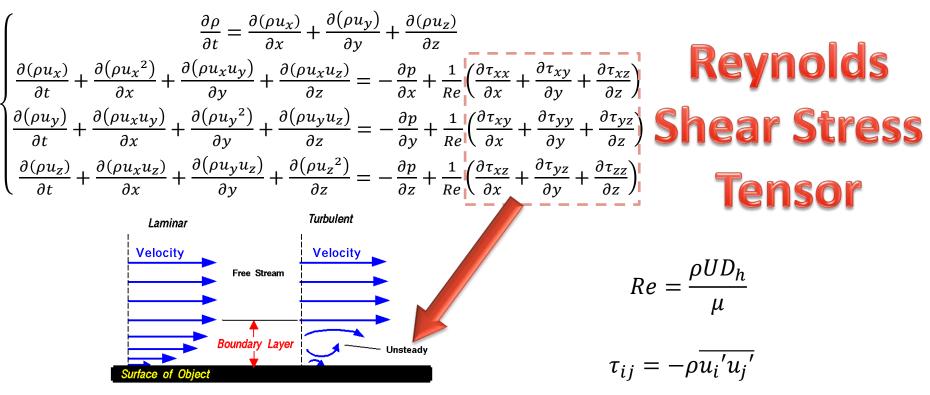




 Averaging may lead to non-conservative conclusions!







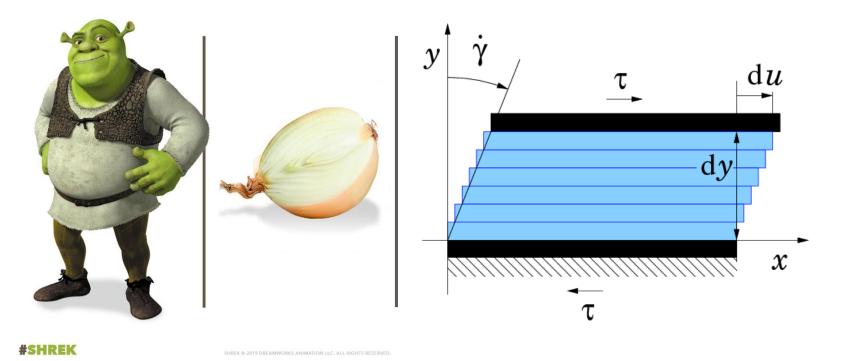
Velocity is zero at the surface (no - slip) Source: www.grc.nasa.gov/www/k-12/airplane/boundlay.html



They are all made of layers

Source: knowyourmeme.com/photos/1490591-shrek



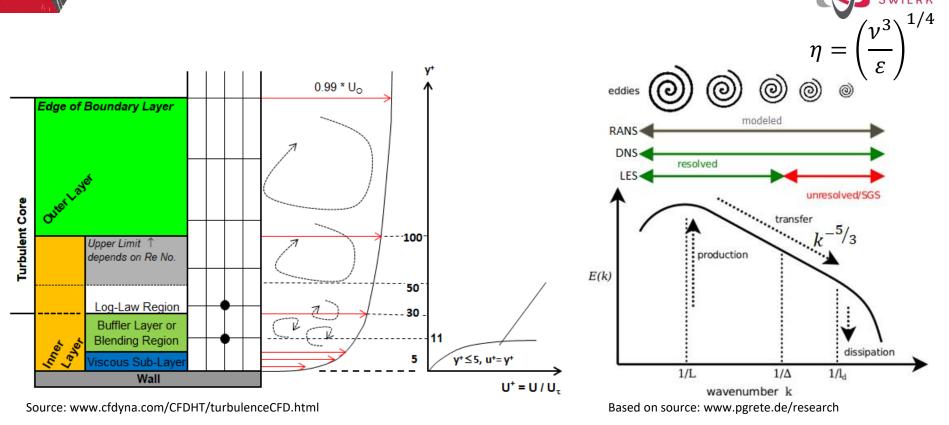


Source: de.wikipedia.org/wiki/Schergeschwindigkeit

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Boundary Layer and Energy Cascade



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Approach	AR	Physical shape
RANS*	75	
LES*	15	
DNS	1	

(*) 1.1 < Cell Layer Growth Rate < 1.3

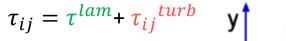


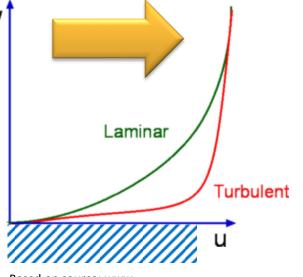




So instead of tensor, like this: In RANS, one solves this*:

$\left(\frac{\partial \tau_{xx}}{\partial x}\right)$	$+ \frac{\partial \tau_{xy}}{\partial y} + \frac{\partial \tau_{xz}}{\partial z} \Big)$
$\left(\frac{\partial \tau_{xy}}{\partial x}\right)$	$+ \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{yz}}{\partial z} $
$\left(\frac{\partial \tau_{xz}}{\partial x}\right)$	$+ \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} \Big)$





Based on source: www-

mdp.eng.cam.ac.uk/web/library/enginfo/aerother mal_dvd_only/aero/fprops/introvisc/node8.html

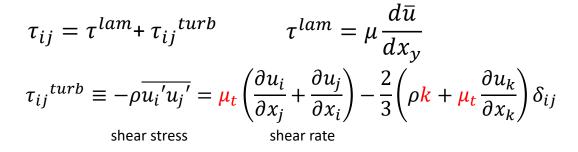




So instead of tensor, like this:

$\left(\frac{\partial \tau_{xx}}{\partial x}\right)$	$+\frac{\partial \tau_{xy}}{\partial y}+\frac{\partial \tau_{xz}}{\partial z}$
$\left(\frac{\partial \tau_{xy}}{\partial x}\right)$	$+ \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{yz}}{\partial z} \Big)$
$\left(\frac{\partial \tau_{xz}}{\partial x}\right)$	$+\frac{\partial \tau_{yz}}{\partial y}+\frac{\partial \tau_{zz}}{\partial z}\Big)$

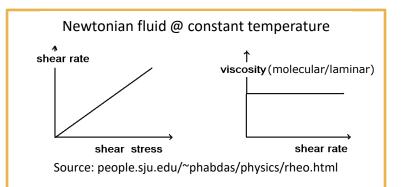
: In RANS, one solves this*:



"(...) The Eddie Viscosity hypothesis was posed for making the things simpler, in the sense that the turbulent Reynolds stresses (which are ugly and nonlinear in velocity perturbations) are simplified to be proportional to the gradients of the mean velocity, as happens in Newtonian laminar flows with the viscous stresses. The coefficient of proportionality is termed the Eddie Viscosity, which far from being a constant or fluid property, is a magnitude dependant on the flow field and its solution.

The Eddie viscosity hypothesis is inherently wrong, in that the Reynolds stresses are in general not co-linear with the mean velocity gradients, as has being discovered by DNS solutions. However, the numerical methods stemming from this simplification (such as RANS methods) are low-time consuming and can be used, sometimes massively, by computational fluid dynamists to obtain approximate solutions of turbulent flows." (Clausius2)

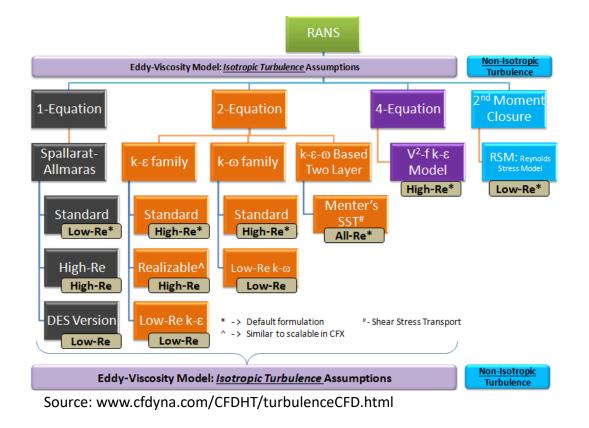
Source: https://www.physicsforums.com/threads/moleculer-viscosity-eddy-viscosity.190265/





RANS models family







RANS example - realizable k-ɛ model (so-called Shih model '94)



$$\mu_t = \rho C_\mu \frac{k^2}{\varepsilon}$$





Implemented by

$$\frac{\partial}{\partial t}(\rho k) + \frac{\partial}{\partial x_j}(\rho k u_j) = \frac{\partial}{\partial x_j} \left[\left(\mu + \frac{\mu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right] + G_k + G_b - \rho \varepsilon - Y_M + S_k$$

$$\frac{\partial}{\partial t}(\rho\varepsilon) + \frac{\partial}{\partial x_j}(\rho\varepsilon u_j) = \frac{\partial}{\partial x_j}\left[\left(\mu + \frac{\mu_t}{\sigma_\varepsilon}\right)\frac{\partial\varepsilon}{\partial x_j}\right] + \rho C_1 S\varepsilon - \rho C_2 \frac{\varepsilon^2}{k + \sqrt{\nu\varepsilon}} + C_{1\varepsilon} \frac{\varepsilon}{k} C_{3\varepsilon} G_b + S_{\varepsilon}$$

 G_k generation of turbulence kinetic energy due to the mean velocity gradients,

 G_b generation of turbulence kinetic energy due to buoyancy,

 Y_M represents the contribution of the fluctuating dilatation in compressible turbulence to the overall dissipation rate, S modulus of the mean rate-of-strain tensor

$$C_{1} = \max \left[0.43, \frac{Sk}{Sk + 5\varepsilon} \right]$$

$$C_{2} \text{ and } C_{1\varepsilon} \text{ are constants,}$$

$$C_{3\varepsilon} = \tanh \left| \frac{u_{\parallel g}}{u_{\perp g}} \right|$$

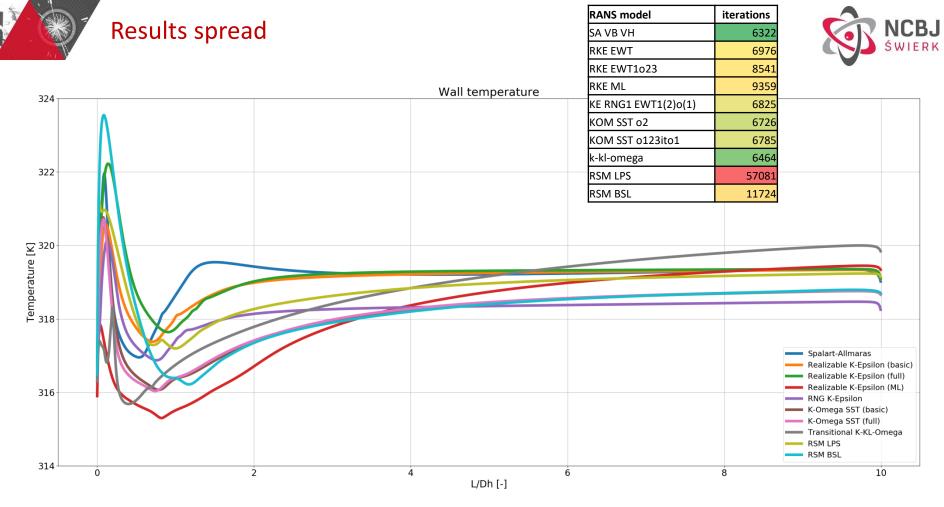
$$\sigma_{k} \text{ and } \sigma_{\varepsilon} \text{ are the turbulent Prandtl numbers,}$$

$$S_{k} \text{ and } S_{\varepsilon} \text{ are user-defined source terms.}$$

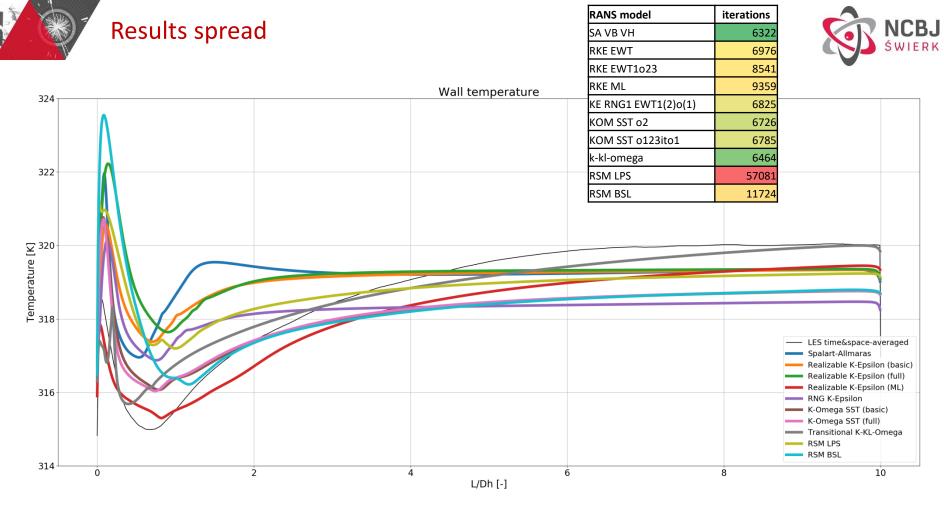
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$$k = \frac{1}{2} \left(\overline{(u_x')^2} + \overline{(u_y')^2} + \overline{(u_z')^2} \right)$$

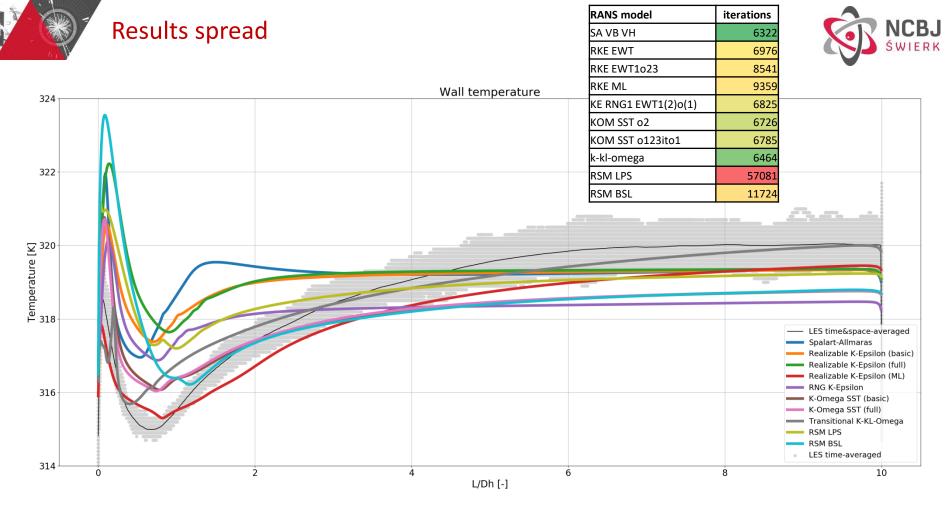
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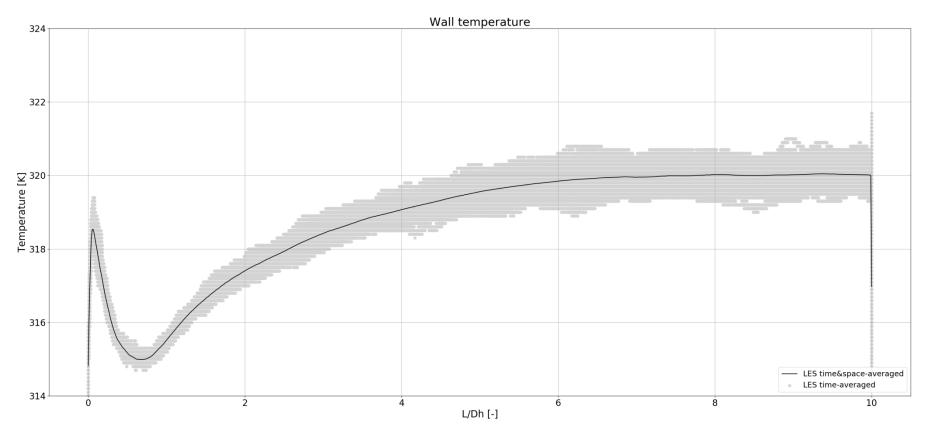
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Results spread



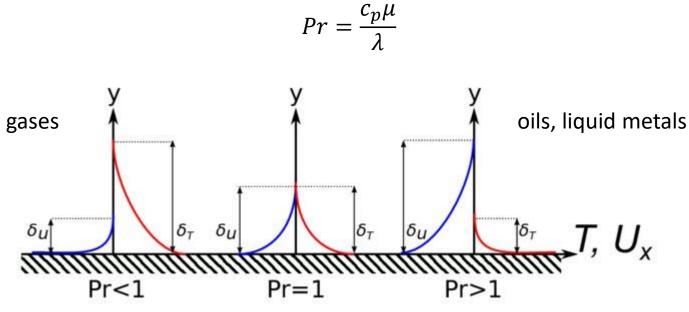


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Tricky boundary layer



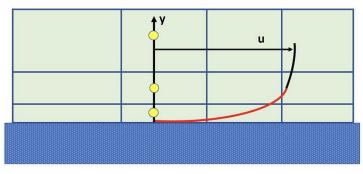


Based on source: Thiele R. (2015), DOI: 10.13140/RG.2.1.4741.5123





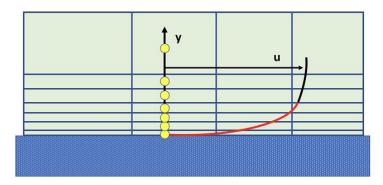
 Logarithmic-based Wall functions to resolve boundary layer



Source: www.simscale.com/forum/t/what-is-y-yplus/82394

- Recommended approach when:
 - High Re flow is to be simulated

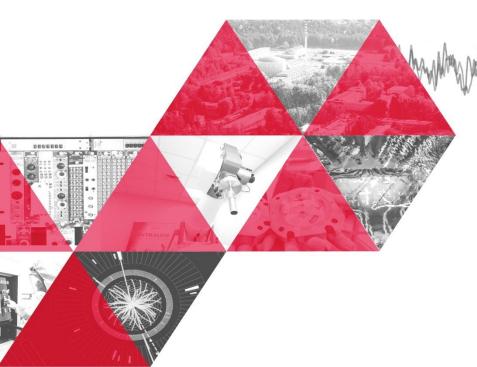
 Viscous sublayer resolving approach to resolve boundary layer



- Recommended approach when:
 - Forces on the wall are important
 - Heat transfer
 - Detached flow

Thank you for attention





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